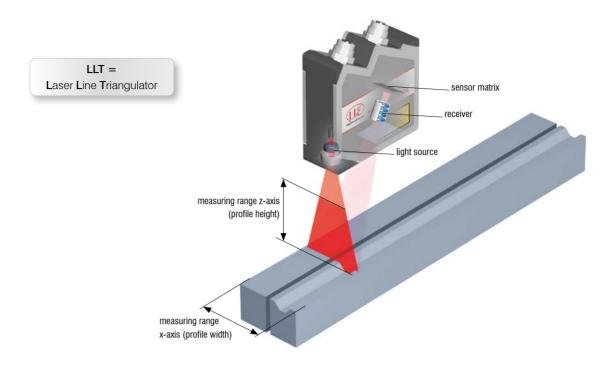


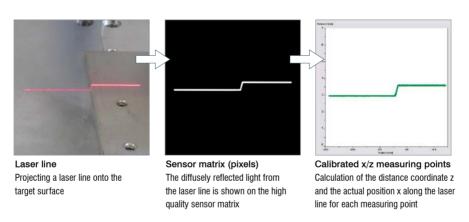
# More Precision

scanCONTROL // 2D/3D laser scanner (laser profile sensors)









### What are laser scanners?

Laser scanners from the LLT series record, measure and evaluate profiles on a variety of different target surfaces. With its scanCONTROL/gapCONTROL series, Micro-Epsilon offers from the preconfigured sensors to the complex measuring systems all from a single source.

### The measuring principle

Laser scanners - often referred to as profile sensors - use the laser triangulation principle for two-dimensional profile detection on different target surfaces. By using special lenses, a laser beam is enlarged to form a static laser line and is projected onto the target surface. The optical system projects the diffusely reflected light of this laser line onto a highly sensitive sensor matrix. In addition to distance information (z-axis), the controller also uses this camera image to calculate the position along the laser line (x-axis). These measured values are then output in a two-dimensional coordinate system that is fixed with respect to the sensor. In the case of moving objects or a traversing sensor, it is therefore possible to obtain 3D measurement values.

# scanCONTROL gapCONTROL

### Customer evaluation

These models provide calibrated profile data which can be further processed on a PC using a customer software evaluation.

### Integrated evaluation

These models provide selected measurement values.

The parameter set up for the sensors and the measurement programs is stored in the integrated controller.

	COMPACT	HIGHSPEED	SMART	GAP
	Laser scanners for common measurement tasks	Laser scanners with fast profile frequency	Laser scanners with comprehensive software	Laser scanners with software specifically developed for gap measurements
LLT26xx 640 points/profile Profile frequency Standard up to 300Hz High speed up to 4000Hz	scanCONTROL 2600 ▶ Page 10	scanCONTROL 2650 ▶ Page 10	scanCONTROL 2610  ▶ Page 10	gap <mark>CONTROL</mark> 2611  ▶ Page 10
LLT29xx  1280 points/profile Profile frequency Standard up to 300Hz High speed up to 2000Hz Available with red or blue diode	scan <mark>CONTROL</mark> 2900 ▶ Page 12	scanCONTROL 2950 ▶ Page 12	scanCONTROL 2910 ▶ Page 12	gap <mark>CONTROL</mark> 2911  ▶ Page 12
	Integration: SDK for and examples for the state of the st		Evaluation: scanCONTROL Configuration Tools Page 22	Evaluation: gapCONTROL Setup Software  Page 24

## Transmission of calibrated profile data

### COMPACT

HIGHSPEED

The COMPACT sensors are used for providing calibrated profile data for external profile analysis, for example, on a PC. They are suitable for static and dynamic measurements.

An Ethernet interface allows the user to configure the sensor via a PC application, as well as to transmit profile data. More details about the software interface can be found in the "Integrating scan-CONTROL in application software" chapter.

The HIGHSPEED models are also used to transmit the calibrated profile data. With a profile frequency of up to 4000Hz, these sensors offer everything for advanced high speed and 3D applications

Parameter set up via customer software application



Individual further processing of calibrated profile data

# Measurement data output

### **SMART**

The scanCONTROL SMART series offers plug & play solutions for simple-to-complex measurement tasks, eliminating the need for any external controller or PC.

Set up and configuration of the sensor is carried out via the scanCONTROL Configuration Tools PC software, which enables the measurement of steps, angles, seams and grooves. The parameter sets are stored in the sensor which is why the sensor autonomously performs measurements without requiring any external control devices or PCs.

Parameter set up via scanCONTROL Configuration Tools/gapCONTROL Setup Software

### GAP

The GAP class offers a plug & play solution especially for gap measurements. The gapCONTROL Setup Software enables the necessary set up and configuration for different gap types and to store them in the sensor.

Profile analysis in the sensor head, transmission of measured values

## Advanced technology

- Up to 1280 points per profile
- Measurement frequency up to 4000 profiles/sec.
- Compact size
- Integrated evaluation without any external controller or IPC
- Factory calibration for metals
- Made / Developed in Germany
- Numerous references worldwide
- Proven high operational safety in the 24/7 operation over many years
- Real Time Surface Compensation

### Different laser types

- 2M class (red)
- = 3B class (red)
- Blue Laser



### **Universal** application

- Inline measurement of gap, profile, step, angle, ...
- Provides 3D information and images for image processing
- Profile transmission or measurement data output
- Robust: for use in processing lines and laboratories
- Also suitable for use with robotic applications
- Multi scanner applications
- Versions for integrators and end users



Edge

### **Interfaces**

- Gigabit Ethernet (GigE Vision)
- Trigger and encoder input
- Gateway for PROFINET, EtherNet/IP and EtherCAT
- Output Unit for analog outputs and switch signals
- Power over Ethernet (PoE) only one cable
- Secure measurement data output via Modbus
- Fast measurement data output via UDP
- Direct communication using PLC



### Comprehensive software

- SMART and GAP classes:
- Analysis and evaluation directly in the sensor head
- Configuration software provides ease of use
- Libraries for C, C++, C#
- LabVIEW driver
- Linux implementation
- Free software, libraries and firmware updates

# Real Time Surface Compensation: Dynamic adaption to rapidly changing surfaces

Laser profile scanners use the diffusely reflected laser light. The intensity of reflection is (highly) dependent on the surface properties like color, shininess and light absorption of the measurement target.

The Real Time Surface Compensation feature of the sensors permits reliable measurements of constantly changing surface conditions. Real time adaption of exposure time and the threshold of reflection detection enable you to get stable measurement results in fast-changing measurement situations without having to adapt the sensor settings manually.

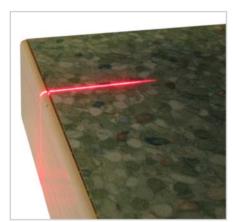


### scanCONTROL / gapCONTROL

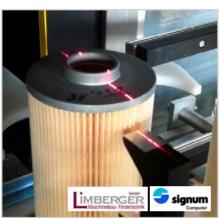
### Sensor, solution and system from a single source

Micro-Epsilon has many years' experience in integrating highly efficient laser line sensors to customer applications and in supplying complete systems from a single source.

LLT sensors are adapted to a variety of common applications in quality control, production processes and automation.



Defect recognition on worktops



Filter height in the automotive industry



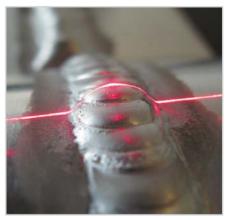
V-gap measurement on pipes



Gap measurement on a car body



Profile measurements on brake disks



Measuring weld seam profiles



Tyre inspection



Distance measurement at the centre console



Inspection of the adhesive beading

### scanCONTROL / gapCONTROL BL

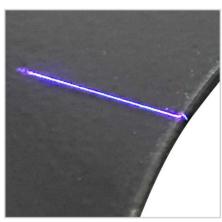
The laser scanners with blue laser line are used for multi-dimensional measurement on red-hot glowing metals as well as on transparent and organic materials. While allowing higher stability, the blue laser light does not penetrate the measurement object due to the shorter wavelength of the blue-violet laser. Compared to red lasers, blue laser sensors enable more reliable measurements on red-hot glowing and organic objects. The high-focused, blue laser line enables furthermore to use laser scanners with 10mm line length in highest precision.



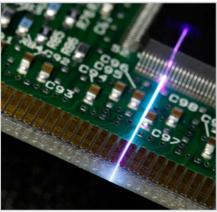
Blade angle of razors



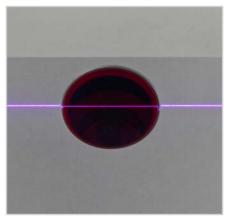
Production of steel-forged rings



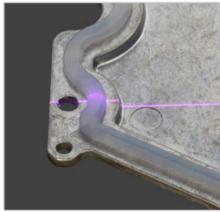
Burr measurement on punching sheets



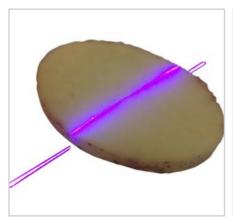
Position of electronic components



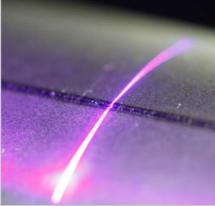
Gap measurement of inserted glass



Inspection of silicone adhesive beading



Thickness measurement of potato slices



Completeness of laser welding seams



Thermal tests

### Technical details and versions

### scanCONTROL 26x0 gapCONTROL 26x1



- z-axis measuring range up to 265mm
- x-axis measuring range up to 143.5mm
- Profile frequency up to 4,000Hz
- Measuring rate up to 2,560,000 points/sec
- z-axis reference resolution from 2µm
- Resolution x-axis up to 640 points

### Compact design suitable for all measurement tasks

The design of the LLT 26xx series is focussed on compact size and low weight. The controller is integrated in the housing, simplifying cabling arrangements and mechanical integration. Due to its compact design and the profile frequency of up to 4000 profiles/sec., the 26xx series is especially suitable for dynamic and robotic applications.

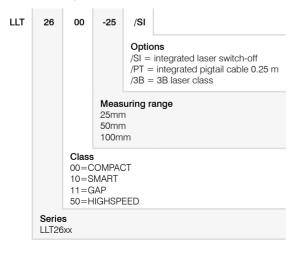
### Interfaces for universal integration

The multi-function port can be used for power supply, as data output, for switching parameters, as trigger input or for synchronizing several scanCONTROL sensors. During synchronous operation, an integrated mode can be used to operate the sensors alternately compensating for overlapping laser lines. One scanner is measuring whilst the other laser line is switched off.

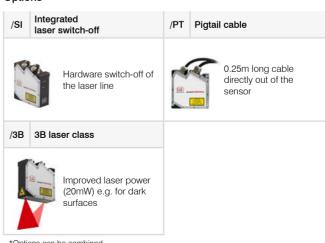
The scanners can be supplied via Ethernet if necessary. If Industrial Ethernet is used as data output, only one cable will remain that connects the sensor to the periphery.

For all SMART and GAP class sensors, the measurement data output can be carried out in different ways, e.g. via Ethernet UDP, Modbus TCP or serial. Micro-Epsilon converters enable data transmission via analog signals, digital switching signals, PROFINET, Ethernet/IP or EtherCAT.

### Article description structure



### Options\*



\*Options can be combined

Accessories from page 18

### Technical details

Model		LLT	26xx-25	26xx-50	26xx-100		
		Start of measuring range	53.5mm	70mm	190mm		
Standard measuring range  Extended measuring range		Midrange	66mm	95mm	240mm		
		End of measuring range	78.5mm	120mm	290mm		
		Height of measuring range	25mm 50mm 100mm				
Extended measuri	na rango	Start of measuring range	53mm 65mm 12:		125mm		
Extended measuri	rig range	End of measuring range	79mm 125mm 390mm				
Linearity 1)		(2sigma)	±0.10% FSO	±0.10% FSO	±0.13% FSO		
Reference resoluti	on <sup>2) 3)</sup>		2µm	4µm	12µm		
		Start of measuring range	23.4mm 42mm 83.1mr				
Standard measuri	na range	Midrange	25mm 50mm		100mm		
ota raara moacan		End of measuring range	29.1mm	58mm	120.8mm		
		Start of measuring range	23.2mm	40mm	58.5mm		
Extended measuri	ng range	End of measuring range	29.3mm	60mm	143.5mm		
Danak diana wasin		Life of measuring range	29.511111		140.011111		
Resolution x-axis				640 points/profile			
D (1) (		COMPACT / SMART / GAP	up to 300Hz				
Profile frequency		HIGHSPEED	up to 4,000Hz				
				Output of measurement values			
		Ethernet GigE Vision	Output of measurement values Sensor control Profile data transmission				
	Ħ		Mode switching				
Interfaces	<u>6</u>	Digital inputs Encoder Trigger					
	ctio		ingger Output of measurement values				
	-ifu	DC 400 (half dupley) 4)	Sensor control				
Interfaces Trod uoitoun Wniti function		RS422 (half-duplex) 4)		Trigger			
			F.1	Synchronisation	DTIN		
Output of measure	ment values		Ethernet (UDP / Modbus TCP); RS422 (ASCII / Modbus RTU)  Analog 5; Switch signal 5				
oatpat of modean	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		PROFINET 6; EtherCAT 6; EtherNet/IP 6				
Display (LED)			1x	laser ON/OFF, 1x power/error/statu	IS		
Light source			Semiconductor laser 658nm (red)				
ū	or lino						
Aperture angle las	CI III IC	standard	20	25° < 8mW (2M laser class)	20		
Laser power		optional	≤ 8mW (2M laser class) < 20mw (3B laser class)				
Integrated lager as	vitch-off	· ·	≤ 20mw (3B laser class)				
Integrated laser sv		optional	Safety interlock, hardware switch-off				
Permissible ambient light (fluorescent light) 2)		South light)	10,000lx IP 65				
Protection class (sensor)			IP 65 acc. EN 61326-1: 2006-10				
EMC		DIN EN 55011: 2007-11 (group 1, B class) EN 61000-6-2: 2006-03					
Vibration		2g / 20 500Hz					
Shock		15g / 6ms					
Operating temperature			0°C to 45°C				
Storage temperature			-20°C to 70°C				
Dimensions			96 x 85 x 33mm				
Weight sensor (without cable)			380g				
· · · · · · · · · · · · · · · · · · ·			11-30VDC, 24V, 500mA,				
Supply		IEEE 802.3af class 2, Power over Ethernet					

<sup>1)</sup> Standard measuring range
2) Measuring object: Micro-Epsilon standard object (metallic, diffusely reflecting material)
3) According to a one-time averaging across the measuring field (640 points)
4) RS422 interface, programmable either as serial interface or input for triggering / synchronisation
5) Only with Output Unit
6) Only with scanCONTROL Gateway
FSO = Full scale output



- z-axis measuring range up to 265mm
- x-axis measuring range up to 143.5mm
- Profile frequency up to 2,000Hz
- Measuring rate up to 2,560,000 points/sec
- z-axis reference resolution from 1µm
- Resolution x-axis up to 1,280 points
- Also available with blue laser

### Compact design for precise measurement tasks

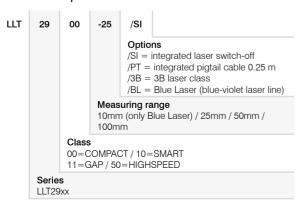
The design of the LLT29xx series is focussed on minimal size and low weight. The controller is integrated in the housing, simplifying cabling arrangements and mechanical integration. Due to its compact design and the high profile resolution, the 29xx series is especially suitable for static, dynamic and robotic applications.

### Interfaces for universal integration

The multi-function port can be used for power supply, as data output, for switching parameters, as trigger input or for synchronizing several scanCONTROL sensors. During synchronous operation, an integrated mode can be used to operate the sensors alternately compensating for overlapping laser lines.

One scanner is measuring whilst the other laser line is switched off. The scanners can be supplied via Ethernet if necessary. If Industrial Ethernet is used as data output, only one cable will remain that connects the sensor to the periphery.

### Article description structure



For all SMART and GAP class sensors, the measurement data output can be carried out in different ways, e.g. via Ethernet UDP, Modbus TCP or serial. Micro-Epsilon converters enable data transmission via analog signals, digital switching signals, PROFINET, EtherNet/IP or EtherCAT.

### Also available with blue laser

The Blue Laser technology uses a laser diode with a shorter wavelength of 405nm. The outstanding characteristics of this wavelength range enable reliable measurements to be made that to date have been difficult to achieve using red laser scanners. Its advantages can be seen particularly well on red-hot glowing metals, (semi-) transparent and organic materials.

### Short measuring range

The laser line of only 10mm enables to reliably detect smallest details. The high profile resolution combined with the blue laser line allow for maximum precision destined for versatile applications, e.g. in the electronics production.

### Options\*

/SI	Integ	rated laser switch-off	/PT	Pigtai	il cable
	1	Hardware switch-off of the laser line	<u> </u>		0.25m long cable directly out of the sensor
/3B	3B las	ser class	/BL	Blue I	laser line
A		Improved laser power (20mW) e.g. for dark surfaces	A		Blue laser line (405nm) for (semi-) transparent, red-hot glowing and organic materials

\*Options can be combined

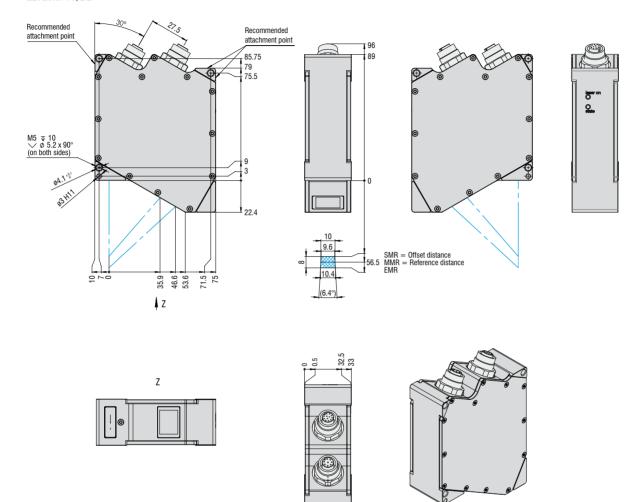
Accessories from page 18

### Technical details

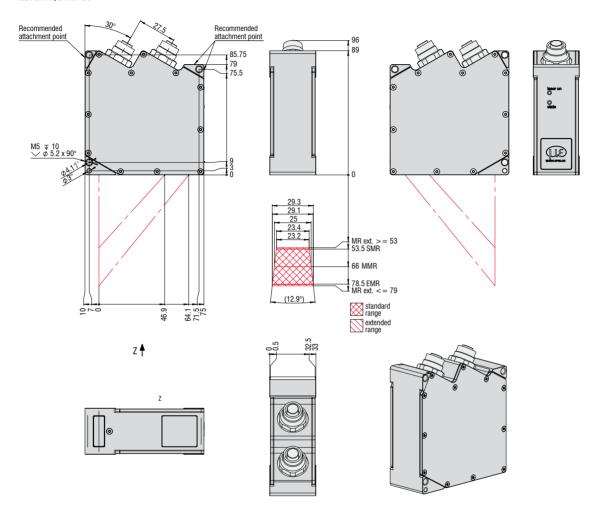
Model		LLT	29xx-10/BL	29xx-25	29xx-50	29xx-100
		Start of measuring range	52.5mm	53.5mm	70mm	190mm
Standard measuring range  Extended measuring range		Midrange	56.5mm	66mm	95mm	240mm
		End of measuring range	60.5mm	78.5mm	120mm	290mm
		Height of measuring range	8mm	25mm	50mm	100mm
Extended measuring range		Start of measuring range	-	53mm	65mm	125mm
		End of measuring range	-	79mm	125mm	390mm
Linearity 1)		(2sigma)	±0.17% FSO	±0.10% FSO	±0.10% FSO	±0.10% FSO
Reference resolu	ution 2) 3)		1 <i>μ</i> m	2µm	4µm	12µm
		Start of measuring range	9.4mm	23.4mm	42mm	83.1mm
Standard		Midrange	10mm	25mm	50mm	100mm
measuring range	9	End of measuring range	10.7mm	29.1mm	58mm	120.8mm
F		Start of measuring range	10.7111111	23.2mm	40mm	58.5mm
Extended measuring range	j.	End of measuring range	-	29.3mm	60mm	143.5mm
0 0		End of measuring range	-			143.511111
Resolution x-axis	3			1,280 poir	nts/profile	
D (1) (		COMPACT / SMART / GAP		up to 3	300Hz	
Profile frequency		HIGHSPEED		up to 2	,000Hz	
		Ethernet GigE-Vision	Output of measurement values Sensor control Profile data transmission			
Interfaces	on port	Digital inputs	Mode switching Encoder Trigger			
	Multi function port	RS422 (half-duplex) 4)	Output of measurement values Sensor control Trigger Synchronisation			
Output of measurement values		Ethernet (UDP / Modbus TCP); RS422 (ASCII / Modbus RTU)  Analog <sup>5)</sup> ; Switch signal <sup>5)</sup> PROFINET <sup>6)</sup> ; EtherCAT <sup>6)</sup> ; EtherNet/IP <sup>6)</sup>				
Display (LED)			1x laser ON/OFF, 1x power/error/status			
Light source standard		Semiconductor laser 405nm (blue)	Semiconductor laser 658nm (red)			
		optional	-	Semi	conductor laser 405nm (	(blue)
Aperture angle la	ser line		10°	20°	25°	25°
Looper		standard		≤ 8mW (2M laser class)		
Laser power		optional	- ≤ 20mw (3B laser class)			
Integrated laser s	switch-off	optional	Safety interlock, hardware switch-off			
Permissible ambi	ient light (fl	uorescent light) 2)	10,000lx			
Protection class (	(sensor)		IP 65			
EMC		acc. EN 61326-1: 2006-10 DIN EN 55011: 2007-11 (group 1, B class) EN 61000-6-2: 2006-03				
Vibration		2g / 20 500Hz				
Shock		15g / 6ms				
Operating temperature		0°C to 45°C				
Storage temperature		-20°C to 70°C				
Dimensions		96 x 118.5 x 33mm 96 x 85 x 33mm				
Weight sensor (without cable)		440g 380g				
		11-30VDC, 24V, 500mA,				
Supply				IEEE 802.3af class 2,		

<sup>&</sup>lt;sup>1)</sup> Standard measuring range
<sup>2)</sup> Measuring object: Micro-Epsilon standard object (metallic, diffusely reflecting material)
<sup>3)</sup> According to a one-time averaging across the measuring field (640 points)
<sup>4)</sup> RS422 interface, programmable either as serial interface or input for triggering / synchronisation
<sup>5)</sup> Only with Output Unit
<sup>6)</sup> Only with scanCONTROL Gateway
FSO = Full scale output

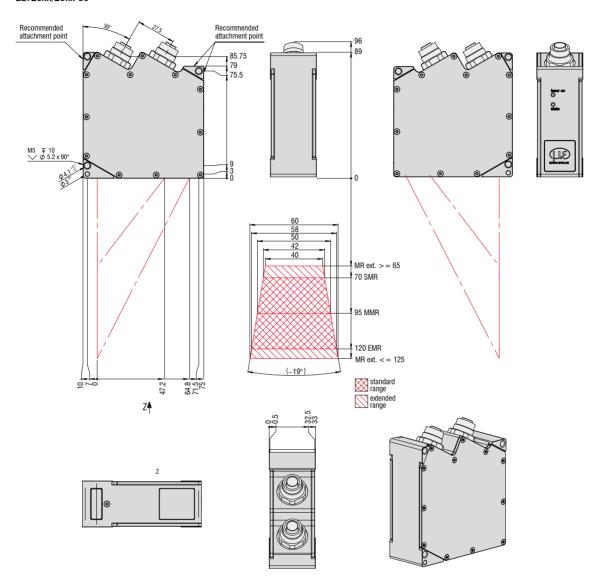
### LLT29xx-10/BL



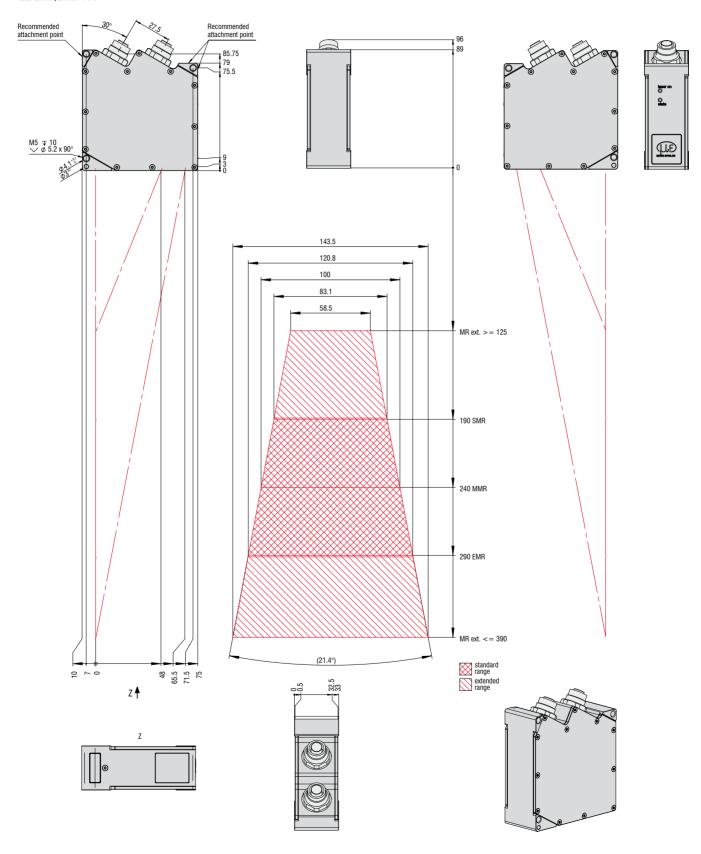
### LLT26xx/29xx-25



### LLT26xx/29xx-50



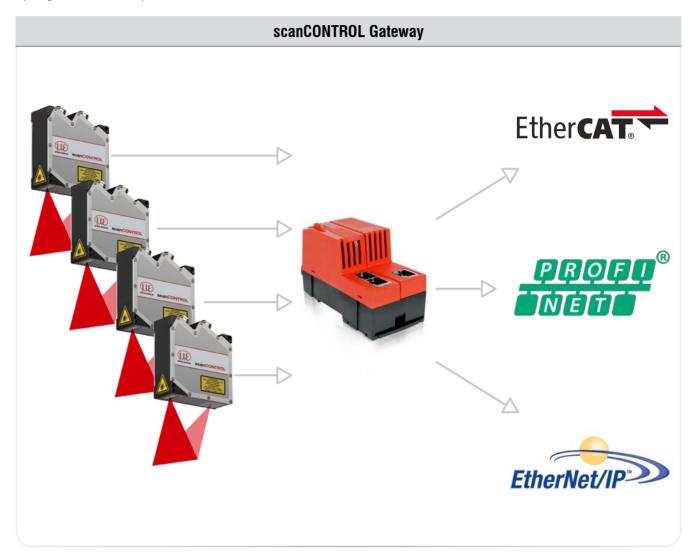
### LLT26xx/29xx-100



### PROFINET / EtherCAT / EtherNet/IP - for all scanners of the SMART and GAP classes

Each scanCONTROL Gateway can be connected with up to 4 sensors. It communicates with the scanCONTROL SMART sensor or the gapCONTROL sensor via Ethernet Modbus. The resultant values are then converted to PROFINET, EtherCAT or EtherNet/IP. The customer carries out the parameter set up with a detailed instruction manual.

\*operating more than one sensor requires a switch.



### Gateway

6414129 scanCONTROL Gateway 6411168 scanCONTROL SPU Switch, 5 ports 6411167 scanCONTROL SPU Switch, 8 ports Fieldbus coupler, configurable for PROFINET, EtherNet/IP and EtherCAT Industrial Ethernet Switch (unmanaged) for mounting rail, 10/100/1000 Mbit/s, 5 ports Industrial Ethernet Switch (unmanaged) for mounting rail, 10/100/1000 Mbit/s, 8 ports

Sensors on the gateway	Max. measurement frequency
1	450Hz
2	240Hz
3	160Hz
4	120Hz

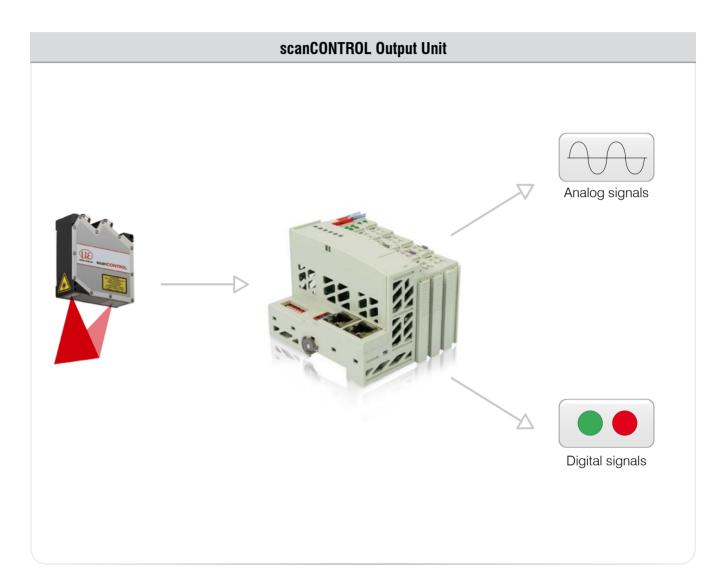
nsors on the gateway	Max. measurement frequency
1	450Hz
2	240Hz





### Analog signals / digital switching signals – for all scanners of the SMART and GAP classes

The scanCONTROL Output Unit is addressed via Ethernet and outputs analog and digital signals. Different output terminals can be connected to the fieldbus coupler.



### **Output Unit**

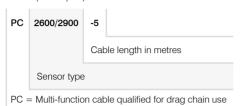
641407	3 Output Unit Basic/ET	Fieldbus coupler with filter module and bus end terminal
032513	1 OU-DigitalOut/8-channel/DC24V/0.5A/negative	8-channel digital output terminal; DC 24V; 0.5A; negative switching;
03251	5 OU-DigitalOut/8-channel/DC24V/0.5A/positive	8-channel digital output terminal; DC 24V; 0.5A; positive switching
03251	6 OU-AnalogOut/4-channel/±10V	4-channel analog output terminal; ±10V
032513	5 OU-AnalogOut/4-channel/0-10V	4-channel analog output terminal; 0-10V
032513	2 OU-AnalogOut/4-channel/0-20mA	4-channel analog output terminal; 0-20mA
032513	3 OU-AnalogOut/4-channel/4-20mA	4-channel analog output terminal; 4-20mA

Further terminals are available on request.

### Connection cable

### Multi-function cable

For power supply, digital inputs (TTL or HTL), RS422 (half-duplex)



PCR = Multi-function cable suitable for use with robots

### Ethernet connection cable

For parameter set up, value and profile transmission



SC= Ethernet connection cable qualified for drag chain use SCR = Ethernet connection cable suitable for use with robots

### Accessories

### Art. No. Model

0323479 Connector/8-pol/LLT2600-2900/Ethernet

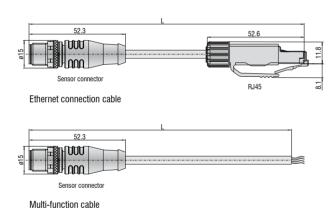
2420067 PS2600/2900

0254072 Suitcase scanCONTROL 26/27/29 MR 10-100

### Description

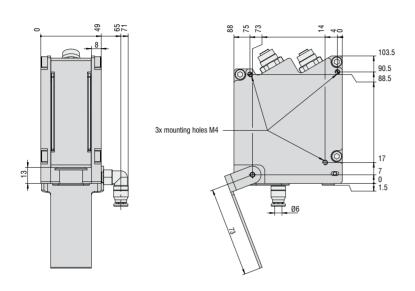
0323478 Connector/12-pol/LLT2600-2900/PS/RS422/DigIN Connector multi-function port for scanCONTROL series LLT26xx and 29xx Connector for Ethernet socket for scanCONTROL series LLT26xx and 29xx Power supply unit for scanCONTROL 2600/2900

Transport suitcase for scanCONTROL sensors, incl. measuring stand



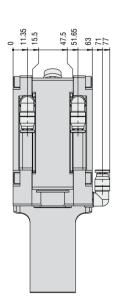
### Protection and cooling housing for LLT26xx and 29xx

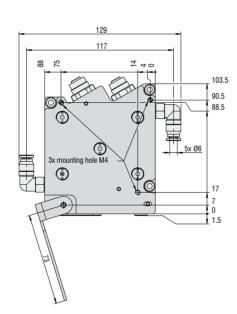
### Protection housing including blow-out system

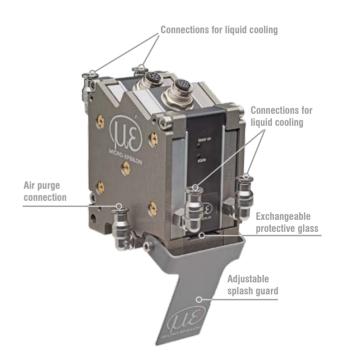




### Protection housing including blow-out system and water cooling







# Art. No.Model2105058scanCONTROL LLT26/29 protection housing2105059Protective scanCONTROL LLT26/29 cooling housing0755075Exchangeable glass for protection housing

### Description

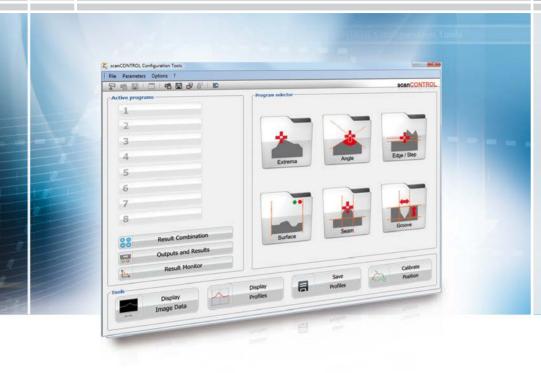
Adaptive protection housing for scanCONTROL 26xx/29xx

Adaptive protection and cooling housing for scanCONTROL 26xx/29xx

Exchangeable glass for protection/cooling concept LLT 26/29, pack. with 50 pcs

### Software

# scanCONTROL Configuration Tools



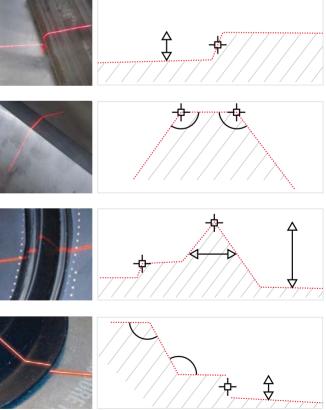
- Plug & Play solution for complex measurement tasks
- Evaluation in the sensor head without external controller
- Parallel execution of different measurement tasks and multiple evaluation
- Easy online and offline analysis

The sensors of the SMART series have an intelligent controller which allows simple profile analysis without an additional PC.

The scanCONTROL Configuration Tools software is used for parameter set up of the profile analysis. As well as configuration of the sensor, this also enables the parameters of the measurement task to be set up and of the outputs, resulting in a compact, industrial, inline measurement solution.

For offline testing of high speed processes, the functions of the software also operate using pre-recorded profiles, without requiring a sensor to be connected.

A complete profile analysis task can be programmed in four simple steps. The pre-configured measuring system operates in standalone mode and transmits the measured values to a PLC.



The system is freely configurable and can be quickly and easily adjusted for a variety of tasks

### Step 1

### Alianment of the sensor

The ,Display Image Data' module will help you to mount the sensor. This shows a live image of the sensor matrix and the optimum measuring range, as well as the reflection characteristics of the target.

### Step 2

#### Sensor setting

Selecting exposure time, profile frequency and other parameters adjust the laser scanner to the desired application. Dynamic algorithms such as the automatic exposure time or the dynamic threshold enable to detect difficult surfaces as well. The software delivers a direct feedback about the achieved saturation and the current scanner profile frequency.

### Step 3

### Selection of measurement programs

Depending on the measurement task, one or more measurement programs can be selected with a simple mouse click. More than 25 modules are available. There are different module groups for the respective, common profile measurement tasks. The measurement programs to the right are suitable for the exemplary profiles above.

### Step 4

### Configuration of measurement programs

Each of these measurement programs can be individually configured. On a simple interface, different methods of interacting with the live measurement signal are available. Therefore, the relevant areas of the signal, for example, can be cut out and reference points set. The results of the individual measurement packages are displayed directly in the profile.

### Step 5

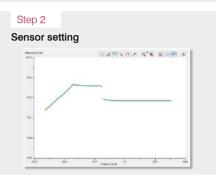
### Defining the outputs and displaying measured values

In the final step, all measurement values are displayed as a profile, filtered temporally if required, and assigned to the different outputs. Limit values and interfaces can therefore be easily configured.

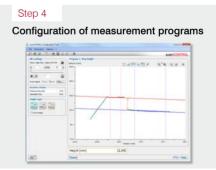
### Download:

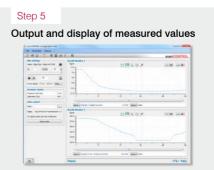
http://www.micro-epsilon.com/configuration-tools

# Step 1 Alignment of the sensor









### gapCONTROL Setup Software



- Plug & Play solution for gap measurements
- Different gap definitions
- Various measurement values (gap width, height offsets, position,...)
- Evaluation in the sensor head without external controller

The following gap main groups are available:

### Basic gaps

The edgeless gaps are the so-called "Basic Gaps" and are characterised by clearly defined reference points for gap measurement. These could be, for example, the end points or the lowest points of each side. Furthermore, the offset of both sides is easily measurable. This gap type allows for an easy entry and the desired measurement result is output by modifying just a few settings.

### Projected gaps

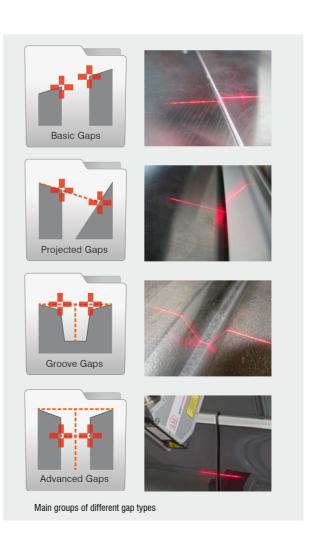
With these types of gaps, the end points of both sides are projected. There are different ways of projection, for example, the projection onto a common parallel or the projection of an end point onto the opposite side. The distance between the projected points is described as gap width. The pre-defined gap variants allow for easy and fast setting.

### Groove gaps

If there is a visible ground in the gap, further inspections can be carried out in order to e.g. measure the gap depth. The evaluations also apply for grooves and other cavities. With soldering applications e.g. the so-called V-gap of pipelines, special algorithms of the "Advanced Groove Gap" output the oscillation width depending on the current soldering depth.

### Advanced gaps

These types offer the user advanced settings. The algorithms for flushness measurement or projection can be adapted independently of each other as well as the search criteria for the respective gap points. Furthermore, these gap types provide numerous additional measured values such as angle or unevenness of the edges.



### gapCONTROL Setup Software

Not all gaps are alike. There are different definitions of how the optical gap is defined for different industries and measuring targets. The gapCONTROL Setup Software enables quick and easy configuration of gapCONTROL sensors. Both components together represent a complete solution for automated gap measurement. After parameterisation, the sensor operates in standalone mode. However, the software can be used for the visualisation of the measured values

### gapCONTROL modes

The user-friendly, intuitive software guides the user through the program. In the first step, a gap mode is chosen from a wide selection of conventional gap types. This pre-selection specifies a start configuration for the chosen gap type. With simple types of gap, e.g. "Edge Points Gap", no additional configuration is needed. Other gap types offer application-specific configuration options.

### Set up and configuration of gap measurements

After selecting the gap mode, the search algorithms for the right and left-hand gap edges as well as for the gap offset are specified with the gapCONTROL Software. For dynamic processes, gapCONTROL also offers tracking functionality, e.g. following the centre position.

### Measurement output: plug & play solution in the integrated controller

For output of measured values, these can be configured with freely assigned values. The configuration of gapCONTROL can be saved in the memory of the sensor. Consequently, the sensor is ready for running in its standalone mode without an external PC. Besides measurement value output via Ethernet (Modbus TCP, UDP) and RS422 (Modbus RTU or ASCII format), additional digital switch signals and analog measuring values can also be output.

### Measurement and evaluation of the measurement value sequence

Using the "Result Monitor" analysis program, selected measurement value sequences of recorded profiles and live profiles can be displayed and analysed, enabling the evaluation of measurements. Additionally, an integrated cgm analysis (capability gauge measurement), and further statistical parameters (e.g. limit value exceeded, average values) are available. The software allows these values to be exported for archive purposes or for further analysis in calculation tables.

### Load and save

The gapCONTROL Setup Software allows both profiles and measuring results (e.g. gap width) to be saved. Stored profiles, even without a gapCONTROL sensor connected, can be re-loaded, and all parameters of the evaluation can be tested on these offline data. Several example profiles are already included with the standard installation of the gapCONTROL Setup Software, and they can largely be used to test the functioning of the software.

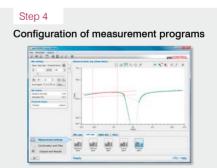
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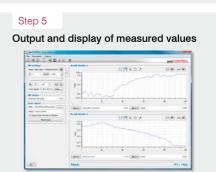
http://www.micro-epsilon.com/gapcontrol-setup-software

# Step 1 Alignment of the sensor









### scanCONTROL 3D-View



- Display of profile sequences
- Offline or real-time display of 3D profiles
- Synchronisation of the direction of travel (e.g. by encoder)
- 2D Export of the profile sequences (PNG)
- 3D Export (ASC, STL, CSV) for CAD programmes
- Intensity per point can be displayed and exported

### 3D visualisation for all scanCONTROL/gapCONTROL models

By means of the relative movement between sensor and target, the third dimension for the measurement data is obtained. The y-coordinates are assigned via a trigger or CMM counter.

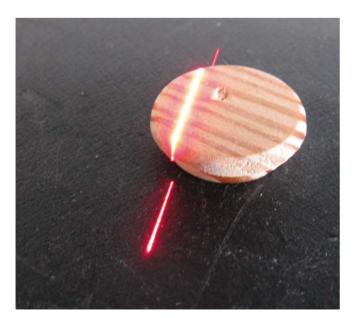
The scanCONTROL 3D-View software is designed for viewing and exporting this 3D data. In addition, 3D-View also supports the configuration of the sensor.

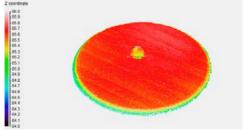
The software enables the interactive viewing of 3D data and the export of this measurement data to common data formats (ASCI, STL or PNG). Various display modes, views and color palettes help in setting up the sensors and analysing the profiles.

The software supports the online visualisation of the profiles as well as offline analysis of stored profile sequences.

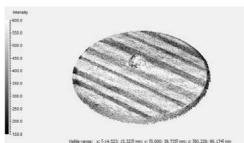
### Download:

http://www.micro-epsilon.com/3d-view

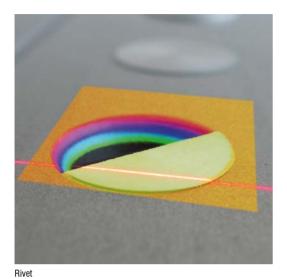


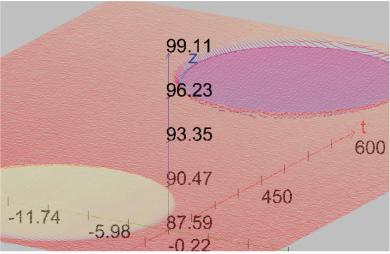


Distance profile

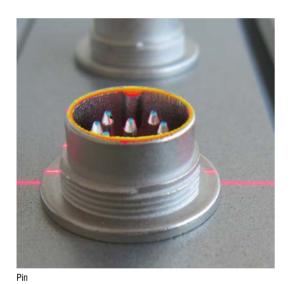


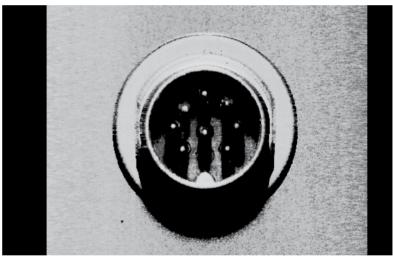
Intensity



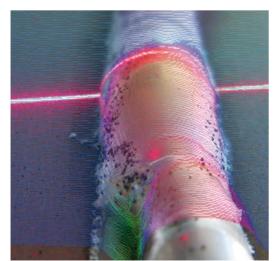


Display mode: "3D view lines"; Color palette "z-coordinates"

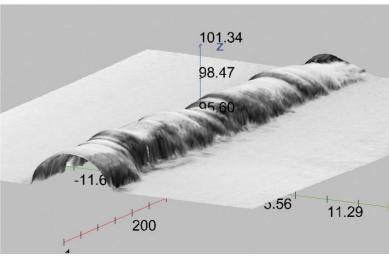




Display mode: "2D view"; Color palette "intensity"







Display mode: "3D view triangles"; Color palette coding "intensity"



The scanCONTROL COMPACT and HIGHSPEED sensors record a profile from individual calibrated points for each measurement. These profiles can be used individually or combined in a container set, and transferred to customer applications as an array or matrix. In addition to the data transfer of individual measuring points and their additional information (e.g. intensity, counter reading) the entire configuration of the sensor can also be controlled from its own application software.

Micro-Epsilon provides a number of interfaces to access the parameter and data transfer functions. The transmission interface primarily used by LLT sensors for communications and profile transfer is Ethernet.

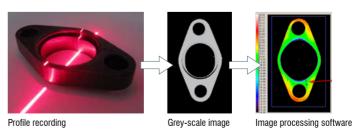
### Ethernet and GigE Vision

Each scanCONTROL sensor complies with the GigE Vision Standard (Gigabit Ethernet for Machine Vision) of the AIA (Automated Imaging Association).

The standard is widely used in the image processing industry and is therefore supported by all conventional computer vision tools, ensuring fast and smooth integration into different image processing software packages - also for 3D evaluation.

GigE Vision ensures optimum data security, perfect performance and short design-in times during implementation. GigE Vision is based on gigabit Ethernet and offers a maximum transfer rate. Ethernet technology offers advantages such as long cable lengths without using repeaters/hubs, and it permits the use of inexpensive network components. The GigE Vision standard provides an open framework for data transmission (e.g. profiles, data sets) and control signals between scan-CONTROL and a PC. The infrastructure topology provides numerous opportunities for single and multiple scanner applications.



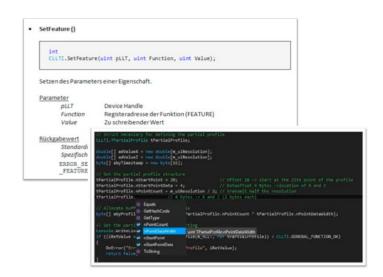


### Integration with the C/C++ library

The C/C++ library for scanCONTROL supports both static and dynamic loading. Both stdcall and cdecl are supported as calling conventions. The individual functions of the library are clearly documented in the interface description and explained using examples.

The scanCONTROL SDK integration package includes:

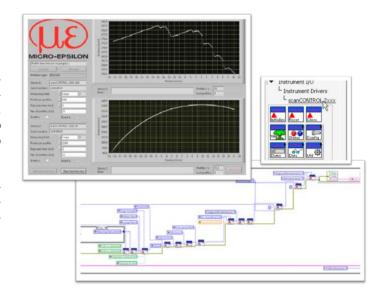
- the LLT.DLL library file
- Interfaces and scanCONTROL documentation
- numerous programming examples for C++ and C#, e.g. for trigger and container mode
- Tool DeveloperDemo.exe for quick testing of the sensor configuration.



### Integration with LabVIEW

The LabVIEW scanCONTROL instrument driver supports fast integration of scanCONTROL sensors into the LabVIEW application environment. For accessing a scanCONTROL sensor and its basic settings, users can drag-and-drop modules directly from the function palette into their VI. Example VIs that illustrate scanCONTROL integration are also included in this package.

The integration of scanCONTROL sensors into the LabVIEW environment is based on the C/C++ library (LLT.DLL) of Micro-Epsilon. Detailed documentation also shows how to set up additional special sensor parameters.

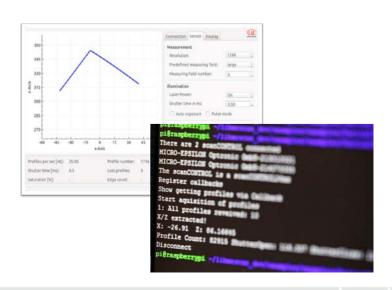


### Integration with Linux

The integration into Linux is performed using an Open Source C library which has been extended by some important control features for scan-CONTROL. An additional C++ library enables fast sensor integration of the entire functionality into a user-friendly API.

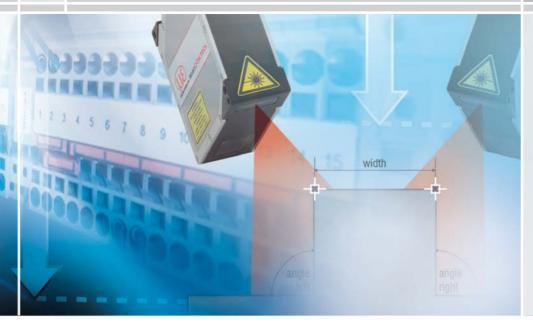
This library is based on the GeniCam standard which is why the sensor can be controlled either via GeniCam commands or directly via the control parameters listed in the documentation. For integration support (e.g. trigger, container mode), also some example programs are available.

Use on ARM embedded PCs (e.g. Raspberry Pi) is possible with restrictions.



### System for multi-scanner applications

### scanCONTROL Smart PLC Unit



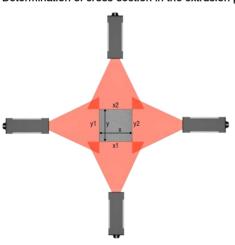
- Measurement value evaluation of up to 8 laser scanners
- Transmission of measured values to higher-level PLC (PROFINET, UDP, Modbus)
- Digital/analog in-/outputs
- Integrated web server for display of results
- Numerous possibilities for recording measurement values

Many applications require several scanners e.g. for contour measurement or when detecting large components. The scanCONTROL Smart PLC Unit is an industrial control unit incl. customised application software for measurement value calculation intended for laser scanners of the scanCONTROL Smart and gapCONTROL product classes.

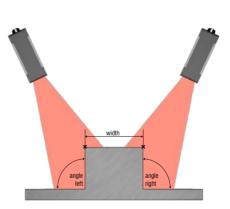
The scanned measurement values are evaluated, displayed, recorded and transmitted to higher-level PLCs using analog and digital interfaces. The modular design of the Smart PLC Unit enables the user to connect up to 8 laser scanners.

### Application examples:

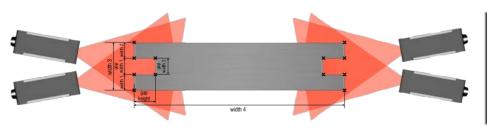
### Determination of cross-section in the extrusion process

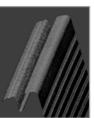


### Contour measurement of a rail



Profile evaluation (profile width, bar width, groove width, groove depth)









### High performance sensors made by Micro-Epsilon



Sensors and systems for displacement and position



Sensors and measurement devices for non-contact temperature measurement



2D/3D profile sensors (laser scanner)



Optical micrometers, fiber optic sensors and fiberoptics



Color recognition sensors, LED analyzers and color inline spectrometer



Measurement and inspection systems